

# Density estimation based on $U$ -divergence

Osamu Komori Prediction and Knowledge Discovery Research Center, Project Researcher

## 1 $U$ -divergence

Let  $U : \mathbf{R}^+ \rightarrow \mathbf{R}$  be a convex and strictly increasing function with the derivative  $u$  and the inverse function  $\xi = u^{-1}$ . Then for real-valued functions  $f$  and  $g : \mathbf{R}^p \rightarrow \mathbf{R}^+$ , the  $U$ -divergence is given as a special case of the Bregman divergence (?):

$$D_U(g, f) = \int d(\xi(g(\mathbf{x})), \xi(f(\mathbf{x})))d\mathbf{x}, \quad (1)$$

where

$$d(g', f') = U(f') - \{u(g')(f' - g') + U(g')\}. \quad (2)$$

Note that  $D_U(g, f)$  is non-negative because of the convexity of  $U$ . The equality holds if and only if  $f = g$  (a.e.  $\mathbf{x}$ ). It is also simply expressed as

$$D_U(g, f) = C_U(g, f) - H_U(g), \quad (3)$$

where

$$C_U(g, f) = - \int g(\mathbf{x})\xi(f(\mathbf{x}))d\mathbf{x} + \int U(\xi(f(\mathbf{x})))d\mathbf{x} \quad (4)$$

$$H_U(g) = - \int g(\mathbf{x})\xi(g(\mathbf{x}))d\mathbf{x} + \int U(\xi(g(\mathbf{x})))d\mathbf{x} (= C_U(g, g)), \quad (5)$$

and  $C_U(g, f)$  and  $H_U(g)$  are called the  $U$ -cross entropy and  $U$ -entropy, respectively.

## $U$ -loss function with volume-mass-one

The  $U$ -loss function for observations  $D = \{\mathbf{x}_1, \dots, \mathbf{x}_n\}$ , which derived from the cross-entropy in (4), is defined as

$$L_U(f) = -\frac{1}{n} \sum_{i=1}^n \xi(f(\mathbf{x}_i)) + \int U(\xi(f(\mathbf{x})))d\mathbf{x}. \quad (6)$$

Then, we consider the following variant:

$$\mathcal{L}_U(f) \equiv L_U(u(U^{-1}(f))) \quad (7)$$

$$= -\frac{1}{n} \sum_{i=1}^n U^{-1}(f(\mathbf{x}_i)) + 1 \quad (8)$$

The point is that the second integral term in (6) is restricted to be 1, which we call volume-mass-one. Here we consider  $U(t) = (1 + \beta t)^{(1+\beta)/\beta} / (1 + \beta)$  with  $\beta > 0$ .

## 2 Algorithm

1. Set  $f_0(\mathbf{x}) = 0$ .

2. For  $k = 1, \dots, K$ ,

(a) Initialize  $\pi = \pi_0 (\ll 1)$ ,  $\Sigma = \mathbf{I}$  and  $\boldsymbol{\mu} = \operatorname{argmin}_{\boldsymbol{\mu} \in D} \left\{ \mathcal{L}_\beta \left( (1 - \pi) f_{k-1}^{1+\beta} + \pi \phi(\boldsymbol{\mu}, \mathbf{I}) \right) \right\}$ , where  $\mathbf{I}$  is the  $p \times p$  identity matrix;  $\phi$  is the basis function in  $\mathcal{D}_\beta$ . Define

$$\mathcal{R}_{\boldsymbol{\mu}, \Sigma} = \left\{ i \mid \frac{\beta}{2(1+\beta)} (\mathbf{x}_i - \boldsymbol{\mu})' \Sigma^{-1} (\mathbf{x}_i - \boldsymbol{\mu}) < 1, \mathbf{x}_i \in D \right\}. \quad (9)$$

(b) For  $\mathbf{x}_i$  such that  $i \in \mathcal{R}_{\boldsymbol{\mu}, \Sigma}$ , calculate

$$q(\mathbf{x}_i) = \frac{\pi \phi(\mathbf{x}_i)}{(1 - \pi) f_{k-1}^{1+\beta}(\mathbf{x}_i) + \pi \phi(\mathbf{x}_i)} \quad (10)$$

$$\boldsymbol{\mu}_q = \frac{\sum_{\mathcal{R}_{\boldsymbol{\mu}, \Sigma}} q(\mathbf{x}_i)^{\frac{1}{1+\beta}} \mathbf{x}_i}{\sum_{\mathcal{R}_{\boldsymbol{\mu}, \Sigma}} q(\mathbf{x}_i)^{\frac{1}{1+\beta}}}. \quad (11)$$

where  $\sum_{\mathcal{R}_{\boldsymbol{\mu}, \Sigma}}$  is the summation of  $i$  over  $\mathcal{R}_{\boldsymbol{\mu}, \Sigma}$ .

(c) Update  $\boldsymbol{\mu} = \boldsymbol{\mu}_q$  and go to step (d) if  $\mathcal{R}_{\boldsymbol{\mu}, \Sigma} \subset \mathcal{R}_{\boldsymbol{\mu}_q, \Sigma}$ ; otherwise go back to step (b).

(d) For  $\mathbf{x}_i$  such that  $i \in \mathcal{R}_{\boldsymbol{\mu}, \Sigma}$ , update  $q(\mathbf{x}_i)$  as in (10) and calculate

$$\Sigma_q = \frac{2 + (2 + p)\beta \sum_{\mathcal{R}_{\boldsymbol{\mu}, \Sigma}} q(\mathbf{x}_i)^{\frac{1}{1+\beta}} (\mathbf{x}_i - \boldsymbol{\mu})(\mathbf{x}_i - \boldsymbol{\mu})'}{2(1 + \beta) \sum_{\mathcal{R}_{\boldsymbol{\mu}, \Sigma}} q(\mathbf{x}_i)^{\frac{1}{1+\beta}}}. \quad (12)$$

(e) Update  $\Sigma = \Sigma_q$  and go to step (f) if  $\mathcal{R}_{\boldsymbol{\mu}, \Sigma} \subset \mathcal{R}_{\boldsymbol{\mu}, \Sigma_q}$ ; otherwise go back to step (d).

(f) For  $\mathbf{x}_i$  such that  $i \in \mathcal{R}_{\boldsymbol{\mu}, \Sigma}$ , update  $q(\mathbf{x}_i)$  as in (10) and calculate

$$\pi_q = \frac{A_2^{1+\beta}}{A_1^{1+\beta} + A_2^{1+\beta}}, \quad (13)$$

where

$$A_1 = \sum_{\mathcal{R}_{\boldsymbol{\mu}, \Sigma}} (1 - q(\mathbf{x}_i))^{\frac{1}{1+\beta}} f_{k-1}(\mathbf{x}_i)^\beta \quad (14)$$

$$A_2 = \sum_{\mathcal{R}_{\boldsymbol{\mu}, \Sigma}} q(\mathbf{x}_i)^{\frac{1}{1+\beta}} \phi(\mathbf{x}_i)^{\frac{\beta}{1+\beta}}, \quad (15)$$

and update  $\pi = \pi_q$ , and  $q(\mathbf{x}_i)$  as in (10).

(g) Repeat the steps from (b) to (f) until the values of  $\boldsymbol{\mu}$ ,  $\Sigma$  and  $\pi$  converges, and set them to be  $\boldsymbol{\mu}_k$ ,  $\Sigma_k$ ,  $\pi_k$ , respectively.

(h) Update  $f_{k-1}$  with  $\phi_k(\mathbf{x}) = \phi_\beta(\mathbf{x}, \boldsymbol{\mu}_k, \Sigma_k)$  and  $\pi_k$  as

$$f_k = \left\{ (1 - \pi_k) f_{k-1}^{1+\beta} + \pi_k \phi_k \right\}^{\frac{1}{1+\beta}}. \quad (16)$$

3. Output  $\hat{f} = f_K$ .

**Theorem 2.1** The empirical loss  $\mathcal{L}_\beta(f_k)$  in the boosting algorithm is monotonically decreasing with respect to  $k$ . That is, for  $k = 1, \dots, K$ ,

$$\mathcal{L}_\beta(f_k) \leq \mathcal{L}_\beta(f_{k-1}). \quad (17)$$

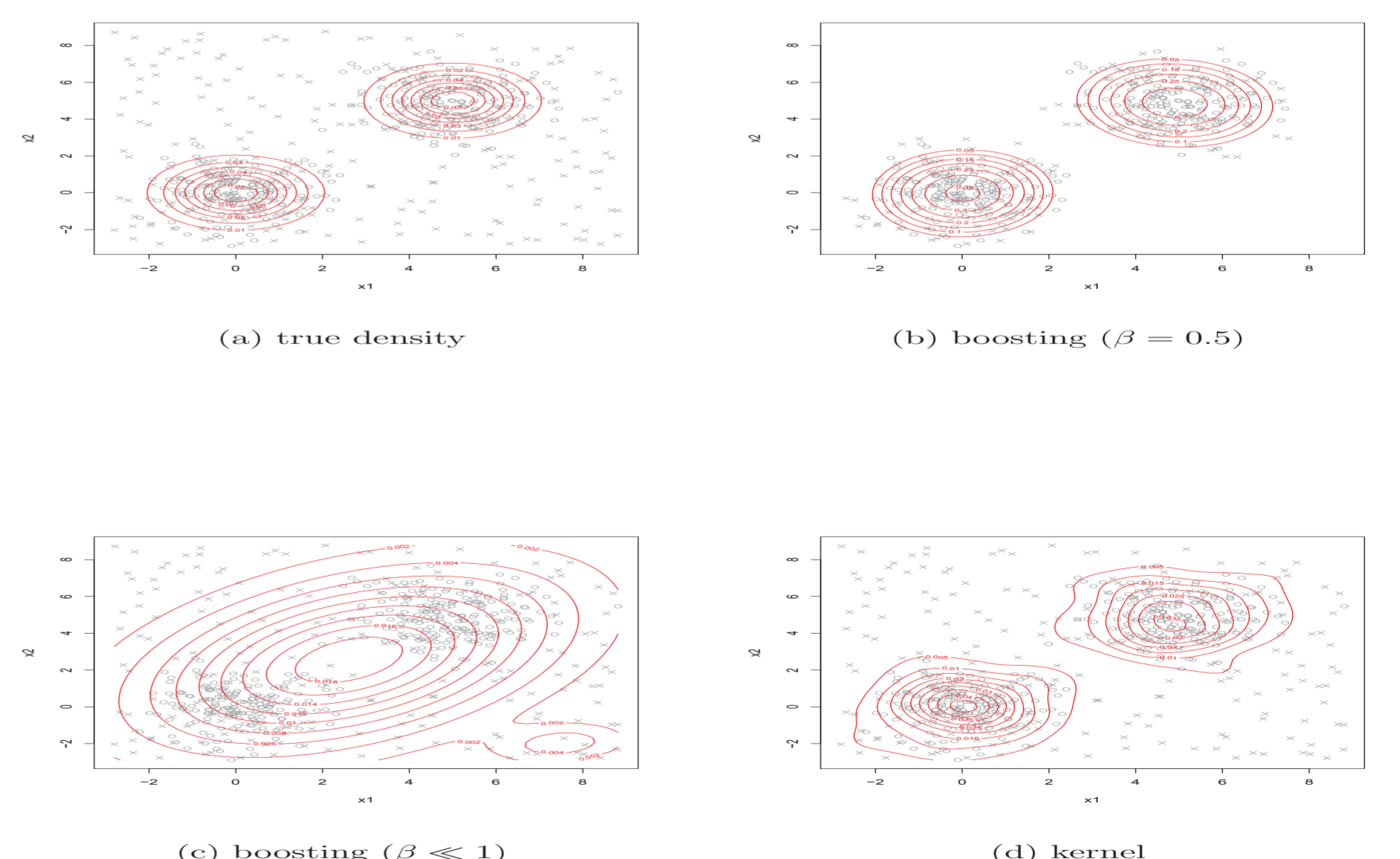


Fig1. Contour plots for the true density (a) and density estimators by three methods (b), (c) and (d). Observations from the normal distributions are denoted by circles; noisy observations are denoted by cross marks. Observations that are not used in the estimation are deleted in the panel (b).