

# AR-モデルにおけるロバスト推定のプログラム

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ROBAR という ALGOL で書かれたプログラムは自己回帰過程のパラメータの最適なロバスト推定量を計算する。未知なパラメータは ETA=データの平均, SGM=イノベーションの標準偏差 TH [1], ..., TH [P]=自己回帰パラメータである。この推定量の定義や効用は Künsch (1983), (1984) にある。

推定量は事前に決めなくてはならない定数 C1, C2 に依存する。もし C1 が増加すれば, TH のロバストネスが減少するけれど, TH の推定効率が增加する。C1 の選択は, ETA と SGM の推定量の性質に無関係である。同様に, C2 は TH の推定量に無関係で, ETA と SGM のロバストネスと効率を調整する。プログラムは, C1 を CMIN とした場合と CMAX とした場合の2つの場合の計算をする。ここで CMIN (CMAX) は, TH の効率が  $1.15^{-1}$  ( $1.05^{-1}$ ) になる値である。C2 も 1.0 と 1.5 の2つの場合が求められる。

AR-モデルの次数 P は, 1 と P MAX の間で変わる。プログラムは, P MAX にどんな値を与えても動く筈であるけれど, P MAX > 10 の時の数値安定性や CPU 時間について, まだ経験がない。

推定量は, Künsch (1983) の方程式

$$(1) \quad \sum_{i=1}^{n-p} w_{c_1} \{r(x_i - \hat{\xi}, \dots, x_{i+p-1} - \hat{\xi}, \hat{\beta}) \hat{u}_{i+p} / \hat{\sigma}^2\} (x_{i+h} - \hat{\xi}) \hat{u}_{i+p} = 0$$

$$(h=0, 1, \dots, p-1),$$

$$(2) \quad \sum_{i=1}^{n-p} w_{c_2} (\hat{u}_{i+p} / \hat{\sigma}) \hat{u}_{i+p} = 0$$

$$(3) \quad \sum_{i=1}^{n-p} w_{c_2} (\hat{u}_{i+p} / \hat{\sigma})^2 \hat{u}_{i+p}^2 = (n-p-1) \alpha \hat{\sigma}^2,$$

ここで

$$w_c(x) = \min(1, c/|x|) \quad (x \in \mathbf{R})$$

$$r(z_1, \dots, z_p, \beta) = \left( \sum_{k=1}^p \sum_{j=1}^p z_k \Lambda_{kj}(\beta) z_j \right)^{1/2}$$

$$\hat{u}_{i+p} = x_{i+p} - \hat{\xi} - \sum_{j=1}^p \hat{\beta}_j (x_{i+p-j} - \hat{\xi})$$

$$\alpha = (2\pi)^{-1/2} \int x^2 w_{c_2}(x)^2 \exp(-x^2/2) dx$$

の解である。ARPAR という PROCEDURE は, ETA と SGM を固定した時の (1) を解く。NUISANCE という PROCEDURE は, TH を固定した時の (2)~(3) を解く。収束まで, このふたつの PROCEDURE を繰り返し使っている。初期値は, 低い次数の推定値を使って INITIAL という PROCEDURE で計算する。しかし, 同じ次数で違う C1 か C2 の推定値が既に求められている時は, それを使う。

MAXLIK という PROCEDURE は, 古典的近似的最尤推定量を計算する。この推定値とロバスト推定値が大きく違っていたら, データの中にモデルに合わない部分がある。例えば, 異常

値や TRANSIENTS 等である。この部分は CHECK というプログラムで見える。

LIN, INCR, MEDIAN, LOCSC, PARCOR は補助の PROCEDURE である。INDATA, OUTCOV と OUTPAR は, INPUT/OUTPUT PROCEDURE である。

AR-モデルをあてはめてから, CHECK というプログラムを用いてデータの DIAGNOSE をする。説明のためロバスト推定量を定義する方程式(1)–(3)をみよう。古典的な推定量と違って重み  $w_{c_1}$  と  $w_{c_2}$  が入る。であるから古典的推定値とロバスト推定値が違ふのは, この重みが1より小さくなるようなデータの部分がある場合である。方程式(2)と(3)の重み  $w_{c_2}$  は, 標準化されたイノベーション  $\hat{u}_i/\hat{\sigma}$  だけに依存する。このイノベーションは INNOV という PROCEDURE が計算する。イノベーションが大きい観測値が含まれていると, ETA と SGM のロバスト推定値と古典的な推定値が違ふ。しかし, イノベーション  $|\hat{u}_i|$  が大きくても必ずしもデータ  $X_i$  が異常値であるとはかぎらない。  $X_i$  の前のデータ  $X[i-1], \dots, X[i-p]$  の中に異常値がある時も  $|\hat{u}_i|$  が大きくなる。だから, CHISQ という PROCEDURE は, 観測値の部分系列  $X[i-Q], \dots, X[i-1]$  ( $i=Q+1, \dots, N$ ) のカイ二乗統計量を計算する。この統計量が大きければ,  $X[i-Q], \dots, X[i-1]$  がモデルに合わない。ある観測値  $X_i$  が異常値かどうかを判断するために  $\hat{u}_i/\hat{\sigma}$  と  $X(i-1), \dots, X(i-p)$  のカイ二乗統計量を見ればよい。(1)の方程式の中の重みは,  $\hat{u}_i$  とカイ二乗統計量の平方根の積に依存する。この重みは, WEIGHT という PROCEDURE が計算する。この重みの系列に小さい部分が含まれていると, TH の古典的推定値とロバスト推定値が違ふ。

例: Künsch (1983) でも使用した 91ヶ月の貸利率 ( $\times 100$ )

INPUT: FILE X. DATA で ROBAR というプログラムの結果は FILE R. DATA (付録)にある。DIAGNOSTICS のため INPUT Y. DATA で CHECK というプログラムの結果は FILE C. DATA (付録)にある。

古典的とロバストな SGM と TH の推定値は違ふ。イノベーションの中では  $|\hat{u}_4|, |\hat{u}_7|, |\hat{u}_{18}|, |\hat{u}_{19}|, |\hat{u}_{28}|, |\hat{u}_{30}|, |\hat{u}_{58}|, |\hat{u}_{77}|$  と  $|\hat{u}_{88}|$  が大きい。カイ二乗統計量 ( $q=1$ ) は  $i=19, i=29$  と  $i=30$  の所で大きい。  $i=18, 19$  のところでは, イノベーションもカイ二乗統計量も大きく, しかも  $u_{18} > 0, u_{19} < 0$  であるから  $i=18$  に additive outlier があると判断する。データのグラフ (Künsch (1983), Fig. 2 を再掲) を見てもすぐわかる。同じように,  $i=28, 29$  で2つ続いて additive outlier があると言える。  $i=4, 7, 58, 77, 88$  の所でそのイノベーションのみ大きいから, ここで, イノベーション異常値があると言える。

WEIGHT  $w_{c_1}$  が小さくなっているところ ( $i=4, 18, 19, 21, 22, 28, 29, 30, 77, 88$ ) と, 上の異常値の所が完全には一致しない。  $w_{c_1}$  がカイ二乗統計量とイノベーションの両方を含んでいるために, 次の場合が起る。まず, 小さなカイ二乗統計量と大きなイノベーションの組み合わせである。例えば  $i=7$  あるいは  $i=58$  を見ればわかる。この場合, その点で不規則性があるけれど, 重みは1である。一方中位の大きさのイノベーションと, 中位の大きさのカイ二乗統計量の組み合わせがありうる。例えば,  $i=21, 22$  をみればわかる。そうすれば何も異常がなくても重みが小さくなる。このような場合, ロバスト推定量が効率を少し失う原因となる。

## 謝 辞

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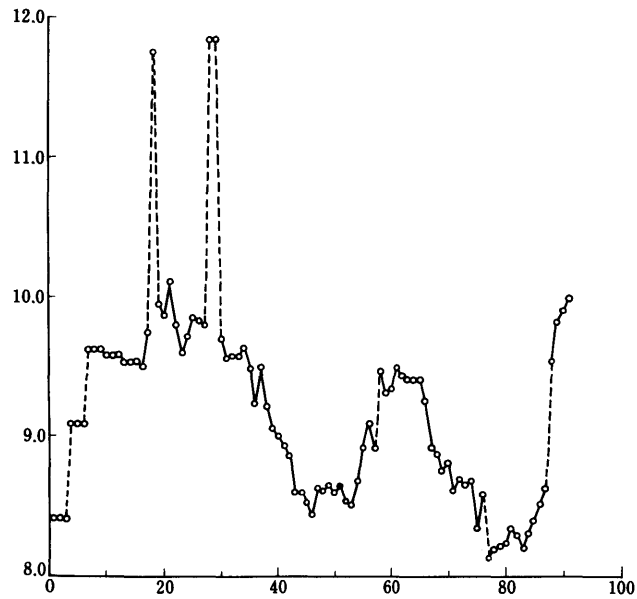


Fig. 1: 91 か月の間の毎月の貸利率のデータ。点線は異常値や怪しいところを表わす。

Monthly lending rate during 91 months. The dotted lines indicate doubtful parts in the data.

(クンシュ[1], Fig. 2 の再掲)

### 参 考 文 献

- Künsch, H. (1983). 自己回帰過程におけるロバスト推定, 統計数理研究所集報 第 31 卷, 51~64.  
Künsch, H. (1984). Infinitesimal Robustness for Autoregressive Processes, *Ann. Statist.*, 12, 843-863.

Programs for Robust Estimation in  
Autoregressive Model Fitting

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Two programs for robust estimation of the parameters of autoregressive models developed in Künsch (1983) are given. The detail of the procedures can be found in the comments of the source lists.

## 付 録

ROBAR

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BEGIN COMMENT THIS PROGRAMM CALCULATES OPTIMAL ROBUST ESTIMATORS
FOR THE PARAMETERS OF AN AR-PROCESS: TH(1),...,TH(P), ETA
AND SGM. HERE ETA=LOCATION OF THE DATA AND SGM=S.D. OF THE
INNOVATIONS. THESE ESTIMATORS ARE DESCRIBED IN KUENSCH,
ANN. STATIST. 12 (1984), AND KUENSCH, PROC. INST. STATIST. MATH.
(SEPTEMBER 1983).
THE ESTIMATORS DEPEND ON TWO CONSTANTS C1 AND C2 TO BE CHOSEN
BEFOREHAND. IF C1 INCREASES, THE ROBUSTNESS OF TH DECREASES,
BUT THE EFFICIENCY OF TH INCREASES. THE CHOICE OF C1 DOES
NOT AFFECT THE PROPERTIES OF ETA AND SGM. C2 REGULATES THE
ROBUSTNESS AND EFFICIENCY OF ETA AND SGM WITHOUT AFFECTING
TH. IN THE PROGRAMM C1 IS PUT EQUAL TO CMIN AND CMAX WHERE
CMIN (CMAX) IS SUCH THAT THE ASYMPTOTIC EFFICIENCY OF TH
IS 1/1.15 (1/1.05). C2 IS PUT EQUAL TO 1.0 AND 1.5.
THE ORDER P OF THE AR-MODEL IS VARIED BETWEEN 1 AND PMAX.
THE PROGRAMM SHOULD WORK FOR ARBITRARY PMAX, BUT WE HAVE NO
EXPERIENCE YET AS REGARDS NUMERICAL STABILITY AND CPU-TIME
FOR PMAX>10.
THE ESTIMATOR IS DEFINED AS THE SOLUTION OF A NON-LINEAR SYS-
TEM OF EQUATIONS WHICH IS SOLVED ITERATIVELY BY THE PROCE-
DURES ARPAP AND NUISANCE. A STARTING VALUE IS CALCULATED BY
THE PROCEDURE INITIAL FROM THE ESTIMATES FOR LOWER ORDER,
BUT IF ALREADY AN ESIMATE FOR THE SAME ORDER, BUT DIFFERENT
C1 OR C2 IS AVAILABLE, WE USE THIS ONE AS STARTING VALUE.
THE PROCEDURES INITIAL, ARPAP AND NUISANCE SHOULD BE FLEXIBLE
ENOUGH FOR MODIFICATIONS, E.G. IF ONE WANTS TO CALCULATE ONLY
ESTIMATES FOR CERTAIN ORDERS BETWEEN 1 AND PMAX.
THE PROCEDURE MAXLIK IS INCLUDED FOR AN EASY COMPARISON OF
CLASSICAL MAXIMUM LIKELIHOOD AND ROBUST ESTIMATES.
THE PROCEDURES LIN, INCR, MEDIAN, LOCSCL, PARCOR ARE AUXILIARY
ONES USED AT DIFFERENT PLACES. FINALLY INDATA, OUTCOV AND
OUTPAR ARE INPUT/OUTPUT PROCEDURES.
INPUT:
  N=LENGTH OF DATA VECTOR
  PMAX=HIGHEST ORDER OF THE MODELS TO BE FITTED
  X=DATA VECTOR
INPUT-CHANNEL: 3
INPUT-FORMAT:
  N,PMAX: 'B3ZD,B2ZD/' (MAIN PROGRAMME, ST-NO 2)
  X: '(12(-2ZDB)/)' (PROCEDURE INDATA).
OUTPUT:
  ML-ESTIMATES FOR ORDERS 1,...,PMAX,
  SAMPLE COVARIANCES FOR LAGS 0,...,PMAX,
  ROBUST ESTIMATES AND CORRESPONDING COVARIANCES
  FOR ORDERS 1,...,PMAX, AND ROBUSTNESS CON
  STANTS C1=CMIN,CMAX, C2=1.5,1.0,
  INITIAL AND INTERMEDIATE ESTIMATES ARE PRINTED,
  A WARNING IS PRINTED IF ANY OF THE ITERATIVE PRO
  CEDURES DOES NOT CONVERGE WITHIN 10 STEPS,
OUTPUT-CHANNEL:1;
INTEGER I,J,K,N,PMAX,P,NI,NIT;

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COMMENT RECURSIVE SOLUTION OF YULE-WALKER EQUATIONS FOR          00001770
      ORDERS 1 UP TO P;                                          00001780
A(1,1):=COV(0);                                                  00001790
N1:=1;                                                            00001800
FOR J:=1 STEP 1 UNTIL P DO BEGIN                                  00001810
  Z:=0.0;                                                         00001820
  FOR I:=1 STEP 1 UNTIL J-1 DO                                     00001830
    Z:=Z+A(J,I)*COV(J-I);                                         00001840
    A(J+1,J):=Z:=(COV(J)-Z)/A(J,J);                                00001850
    A(J+1,J+1):=A(J,J)*(1-Z**2);                                   00001860
    FOR I:=1 STEP 1 UNTIL J-1 DO BEGIN                             00001870
      A(J+1,I):=A(J,I)-Z*A(J,J-I);                                00001880
      INIT(N1):=A(J+1,I);                                          00001890
      N1:=N1+1;                                                    00001900
    END I;                                                         00001910
    INIT(N1):=A(J+1,J);                                           00001920
    INIT(N1+1):=ETA;                                               00001930
    INIT(N1+2):=SQRT(A(J+1,J+1));                                  00001940
    N1:=N1+3;                                                      00001950
  END J;                                                           00001960
FOR I:=1 STEP 1 UNTIL N DO                                        00001970
  X(I):=X(I)+ETA;                                                 00001980
END MAXLIK;                                                       00001990
PROCEDURE INITIAL(N,X,Q,P,TH,COV,SGM,MED,INIT);                  00002000
  VALUE Q,P;                                                       00002010
  INTEGER N,Q,P; REAL SGM,MED; ARRAY X,TH,COV,INIT;              00002020
  COMMENT CALCULATION OF CRUDE INITIAL ESTIMATES FOR THE ORDERS  00002030
    Q+1,...,P IF ESTIMATES FOR THE ORDER Q ARE GIVEN (THE       00002040
    CASE Q=0 IS INCLUDED). THE ESTIMATES ARE BASED ON           00002050
    MEDIAN TYPE ESTIMATES FOR THE CORRELATIONS OF LAG           00002060
    Q+1,...,P WHICH ARE MODIFIED IF POSITIVE DEFINITENESS      00002070
    DOES NOT HOLD.                                              00002080
  INPUT:                                                           00002090
    N=NUMBER OF DATA                                           00002100
    Q,P=ORDERS OF THE MODEL                                     00002110
    MED=MEDIAN OF THE DATA                                     00002120
    TH=AR-PARAMETERS OF THE MODEL OF ORDER Q                   00002130
    SGM=S.D. OF THE INNOVATIONS IN THE MODEL OF ORDER Q       00002140
    COV=COVARIANCES OF LAG<=Q IN THE MODEL OF ORDER Q        00002150
    ONLY THE VALUES COV(K)/COV(0) AND SGM**2/COV(0) ARE      00002160
    ESSENTIAL.                                                  00002170
  OUTPUT:                                                         00002180
    INIT=ESTIMATES FOR THE MODELS OF ORDER Q+1,...,P          00002190
    (IN THE FOLLOWING ORDER: AR-PARAMETERS, LOCATION OF       00002200
    DATA, S.D. OF INNOVATIONS);                                00002210
BEGIN INTEGER N1,I,J,K; REAL U,Z;                                  00002220
  ARRAY A(1:P+1,1:P+1),Y(1:N),R(1:P);                             00002230
  COMMENT CALCULATION OF MEDIAN TYPE CORRELATIONS;               00002240
  FOR I:=1 STEP 1 UNTIL N DO                                       00002250
    X(I):=X(I)-MED;                                              00002260
  FOR K:=1 STEP 1 UNTIL Q DO                                       00002270
    R(K):=COV(K)/COV(0);                                         00002280
  FOR K:=Q+1 STEP 1 UNTIL P DO BEGIN                               00002290
    N1:=0;                                                       00002300
    FOR I:=1 STEP 1 UNTIL N-K DO                                   00002310
      IF ABS(X(I))>0.00001 THEN BEGIN                             00002320
        N1:=N1+1;                                               00002330
        Y(N1):=X(I+K)/X(I);                                       00002340
      END THEN;                                                  00002350
    R(K):=MEDIAN(Y,N1);                                          00002360

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END K;
COMMENT RECURSIVE SOLUTION OF THE YULE-WALKER EQUATIONS FOR
ORDERS Q+1 UP TO P;
FOR I:=1 STEP 1 UNTIL Q DO
  A(Q+1,I):=TH(I);
A(Q+1,Q+1):=SGM**2/COV(0);
FOR J:=Q+1 STEP 1 UNTIL P DO BEGIN
  Z:=0.0;
  FOR I:=1 STEP 1 UNTIL J-1 DO
    Z:=Z+A(J,I)*R(J-I);
  IF A(J,J)<0.5 THEN U:=1.7*A(J,J)**2
  ELSE U:=A(J,J)*(A(J,J)*0.2+0.75);
  IF R(J)>Z+U THEN R(J):=Z+U;
  IF R(J)<Z-U THEN R(J):=Z-U;
  A(J+1,J):=Z:=(R(J)-Z)/A(J,J);
  A(J+1,J+1):=A(J,J)*(1-Z**2);
  FOR I:=1 STEP 1 UNTIL J-1 DO
    A(J+1,I):=A(J,I)-Z*A(J,J-I);
  END J;
COMMENT ROBUST LOCATION AND SCALE ESTIMATES FOR THE INNOVATIONS;
FOR I:=1 STEP 1 UNTIL N DO
  X(I):=X(I)+MED;
N1:=1;
FOR J:=Q+2 STEP 1 UNTIL P+1 DO BEGIN
  Z:=1.0;
  FOR I:=1 STEP 1 UNTIL J-1 DO BEGIN
    INIT(N1):=A(J,I);
    N1:=N1+1;
    Z:=-Z-A(J,I);
  END I;
  FOR I:=1 STEP 1 UNTIL N-J+1 DO BEGIN
    Y(I):=X(I+J-1);
    FOR K:=1 STEP 1 UNTIL J-1 DO
      Y(I):=Y(I)-A(J,K)*X(I+J-1-K);
    END I;
  LOCSC(Y,N-J+1,INIT(N1),INIT(N1+1));
  INIT(N1):=INIT(N1)/Z;
  N1:=N1+2;
  END J;
  X(I):=X(I)+INIT(1);
END INITIAL;
PROCEDURE ARPAR(N,P,X,ETA,SGM,C1,TH,COV,NI);
INTEGER N,P,NI; REAL ETA,SGM,C1; ARRAY X,TH,COV;
COMMENT CALCULATION OF A ROBUST ESTIMATE FOR THE AUTOREG
RESSIVE PARAMETER TH(1),...,TH(P) FOR KNOWN VALUES
OF ETA AND SGM. THE ESTIMATES ARE SOLUTIONS OF "LINEAR"
EQUATIONS SIMILAR TO YULE-WALKER, BUT WEIGHTED SAMPLE CO
VARIANCES ARE USED WHERE THE WEIGHTS DEPEND ON THE UNKNOWN
TH AND THE DATA.
INPUT:
  N=NUMBER OF DATA
  P=ORDER OF THE MODEL
  X=DATA VECTOR
  ETA=MEAN OF THE DATA
  SGM=S.D. OF THE INNOVATIONS
  C1=TRUNCATION POINT OF THE ESTIMATOR
  TH=STARTING ESTIMATE
OUTPUT:
  TH=FINAL ESTIMATE
  COV=COVARIANCES OF THE FITTED MODEL

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00002370  
00002380  
00002390  
00002400  
00002410  
00002420  
00002430  
00002440  
00002450  
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00002480  
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00002500  
00002510  
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      NI=NUMBER OF ITERATIONS NEEDED;                                00002970
      BEGIN INTEGER I,J,K; REAL C,W,U,Z;                             00002980
      ARRAY Y(1:N),DIFF(1:P),A,R(1:P+1,1:P+2);                       00002990
      REAL PROCEDURE WEIGHT(I,P,TH);                                  00003000
      VALUE I,P; INTEGER I,P; ARRAY TH;                             00003010
      COMMENT CALCULATION OF THE WEIGHT OF THE P-TUPLE              00003020
      Y(I),Y(I+1),...,Y(I+P) IN THE MODEL WITH PARAMETERS TH;     00003030
      BEGIN REAL U,V,Z;                                             00003040
      U:=Y(I+P);                                                    00003050
      FOR J:=1 STEP 1 UNTIL P DO                                     00003060
      U:=U-TH(J)*Y(I+P-J);                                         00003070
      Z:=0;                                                          00003080
      FOR J:=0 STEP 1 UNTIL P-1 DO BEGIN                            00003090
      V:=Y(I+J);                                                    00003100
      FOR K:=1 STEP 1 UNTIL J DO                                     00003110
      V:=V-A(J+1,K)*Y(I+J-K);                                       00003120
      Z:=Z+A(J+1,J+1)*V**2;                                         00003130
      END J;                                                         00003140
      WEIGHT:=SQRT(Z)*ABS(U);                                        00003150
      END WEIGHT I;                                                 00003160
      FOR I:=1 STEP 1 UNTIL N DO                                     00003170
      Y(I):=X(I)-ETA;                                               00003180
      NI:=0;                                                         00003190
      ITER:                                                         00003200
      NI:=NI+1;                                                    00003210
      IF NI=11 THEN GOTO ENDE;                                       00003220
      COMMENT CALCULATION OF COVARIANCES AND AR-MODELS OF SMALLER  00003230
      ORDER BASED ON THE OLD TH;                                     00003240
      PARCOR(P,TH,A);                                               00003250
      COV(0):=SGM**2/A(1,1);                                         00003260
      FOR K:=1 STEP 1 UNTIL P DO BEGIN                              00003270
      COV(K):=0.0;                                                  00003280
      FOR I:=1 STEP 1 UNTIL K DO                                     00003290
      COV(K):=COV(K)+A(K+1,I)*COV(K-I);                             00003300
      END K;                                                         00003310
      COMMENT CALCULATION OF WEIGHTED SAMPLE COVARIANCES AND SOLUTION 00003320
      OF THE LINEAR EQUATION;                                       00003330
      C:=C1*SGM**2;                                                00003340
      FOR J:=1 STEP 1 UNTIL P DO                                     00003350
      FOR K:=J STEP 1 UNTIL P+1 DO                                   00003360
      R(J,K):=0;                                                    00003370
      FOR I:=1 STEP 1 UNTIL N-P DO BEGIN                            00003380
      W:=WEIGHT(I,P,TH);                                           00003390
      IF W<C THEN W:=1 ELSE W:=C/W;                                 00003400
      FOR J:=1 STEP 1 UNTIL P DO                                     00003410
      FOR K:=J STEP 1 UNTIL P+1 DO                                   00003420
      R(J,K):=R(J,K)+W*Y(I+J-1)*Y(I+K-1);                         00003430
      END I;                                                         00003440
      FOR J:=1 STEP 1 UNTIL P DO BEGIN                              00003450
      FOR K:=1 STEP 1 UNTIL J-1 DO                                   00003460
      R(J,K):=R(K,J);                                               00003470
      R(J,P+1):=-R(J,P+1);                                         00003480
      END J;                                                         00003490
      LIN(R,P);                                                      00003500
      COMMENT MEASURING THE DIFFERENCE (NEW TH - OLD TH) IN THE METRIC 00003510
      OF THE INFORMATION MATRIX. IF IT IS SMALL, THE ITERATION    00003520
      IS STOPPED;                                                  00003530
      FOR I:=1 STEP 1 UNTIL P DO BEGIN                              00003540
      DIFF(I):=TH(I)-R(P-I+1,P+1);                                  00003550
      TH(I):=R(P-I+1,P+1);                                         00003560

```

```

END I;
Z:=0.0;
FOR K:=0 STEP 1 UNTIL P-1 DO BEGIN
  U:=0.0;
  FOR I:=1 STEP 1 UNTIL P-K DO
    U:=U+DIFF(I)*DIFF(I+K);
    IF K>0 THEN U:=2*U;
    Z:=Z+COV(K)*U;
  END K;
  IF Z>0.002*P*SGM**2/N THEN GOTO ITER;
ENDE:
END ARPAR;
PROCEDURE NUISANCE(N,P,X,TH,C1,ETA,SGM,NI);
  INTEGER N,P,NI; REAL C1,ETA,SGM; ARRAY X,TH;
  COMMENT CALCULATION OF A ROBUST ESTIMATE FOR THE NUISANCE
  PARAMETERS ETA AND SGM FOR KNOWN VALUES OF THE
  AUTOREGRESSIVE PARAMETER TH. CONSIDERING THE INNOVATIONS,
  THIS BECOMES AN I.I.D. LOCATION-SCALE PROBLEM. THE METHOD
  USED IS VARIANT 4 OF HUBER, ROBUST STATISTICS, P.147.
  INPUT:
    N=NUMBER OF DATA
    P=ORDER OF THE MODEL
    X=DATA VECTOR
    TH=AUTOREGRESSIVE PARAMETERS
    C1=TRUNCATION POINT OF THE ESTIMATOR
      (C1 HAS TO BE ONE OF THE VALUES 1.5,1.0,0.5)
    ETA,SGM=STARTING ESTIMATES
  OUTPUT:
    ETA,SGM=FINAL ESTIMATES
    NI=NUMBER OF ITERATIONS NEEDED;
BEGIN
  INTEGER N1,N2,N3,I,J; REAL U,U1,U2,U3,C,C3,EPS;
  INTEGER ARRAY CASE(1:N); REAL ARRAY Y(1:N);
  COMMENT CALCULATION OF INNOVATIONS;
  FOR I:=1 STEP 1 UNTIL N-P DO BEGIN
    Y(I):=X(I+P);
    FOR J:=1 STEP 1 UNTIL P DO
      Y(I):=Y(I)-TH(J)*X(I+P-J);
    END I;
  U:=1.0;
  FOR I:=1 STEP 1 UNTIL P DO
    U:=U-TH(I);
  ETA:=ETA*U;
  IF C1=0.5 THEN C3:=0.0926;
  IF C1=1.0 THEN C3:=0.516;
  IF C1=1.5 THEN C3:=0.7785;
  NI:=0;
ITER:
  NI:=NI+1;
  IF NI=11 THEN GOTO ENDE;
  COMMENT PARTITIONING OF THE INNOVATIONS ACCORDING TO THE OLD
  ETA AND SGM;
  C:=C1*SGM;
  N1:=N2:=N3:=0; U:=0.0;
  FOR I:=1 STEP 1 UNTIL N-P DO BEGIN
    IF Y(I)<ETA-C THEN CASE(I):=1 ELSE
      IF Y(I)<ETA+C THEN CASE(I):=2 ELSE CASE(I):=3;
    IF CASE(I)=1 THEN N1:=N1+1 ELSE
      IF CASE(I)=2 THEN N2:=N2+1 ELSE N3:=N3+1;
    IF CASE(I)=2 THEN U:=U+Y(I);

```

```

END I;
U:=U/N2; U1:=0.0;
COMMENT CALCULATION OF NEW VALUES OF ETA AND SGM;
FOR I:=1 STEP 1 UNTIL N-P DO
  IF CASE(I)=2 THEN U1:=U1+(Y(I)-U)**2;
U2:=SGM;
SGM:=SQRT(U1/((N-P-1)*C3-(N1+N3+(N3-N1)**2/N2)*C1**2));
U3:=ETA; ETA:=U+SGM*C1*(N3-N1)/N2;
EPS:=0.05*SGM/SQRT(N);
IF ABS(SGM-U2)<0.5*EPS & ABS(ETA-U3)<EPS THEN GOTO ENDE;
GOTO ITER;
ENDE:
U:=1.0;
FOR I:=1 STEP 1 UNTIL P DO
  U:=U-TH(I);
  ETA:=ETA/U;
  END NUISANCE;
PROCEDURE OUTPAR(P,I);
INTEGER P,I;
COMMENT PRINTING OF THE PARAMETER ESTIMATES TH,ETA AND SGM
  IN A MODEL OF ORDER P. I IS USED TO DISTINGUISH DIFFERENT
  CASES FOR THE TITLE OF THE OUTPUT;
BEGIN INTEGER J;
  IF I=1 THEN OUTPUTO(1,/'"APPROXIMATED MAX. LIK. ESTIMATES"');
  IF I=2 THEN OUTPUTO(1,/'"CRUDE INITIAL ROBUST ESTIMATES"');
  IF I=3 THEN BEGIN
    OUTPUTO(1,/'"FINAL ESTIMATES WITH ROBUSTNESS CONSTANTS"');
    OUTPUT2(1,/'" C1="ZZ.DD", C2="ZZ.DD',C1,C2);
    END THEN;
  IF I=4 THEN
    OUTPUTO(1,/'"INTERMEDIATE ESTIMATES IN THE RECURSIVE CALCULATION"/');
  IF I<4 THEN OUTPUT1(1,/'" FOR THE ORDER"3Z/' ,P);
  OUTPUTO(1,/'" AR-PARAMETERS"');
  FOR J:=1 STEP 1 UNTIL P DO
    OUTPUT1(1,/'-2Z.3D',TH(J));
    OUTPUT1(1,/'" LOCATION OF DATA:"-5Z.3D',ETA);
    OUTPUT1(1,/'3B"S.D. OF INNOVATIONS:"5Z.3D/' ,SGM);
  END OUTPAR;
PROCEDURE OUTCOV(P);
INTEGER P;
COMMENT PRINTING OF COVARIANCES COV(J), J=0,..P;
BEGIN INTEGER J;
  OUTPUT1(1,/'" CORRESPONDING COVARIANCES FOR LAGS 0,..,"3Z/' ,P);
  FOR J:=0 STEP 1 UNTIL P DO
    OUTPUT1(1,/'-8Z.6D',COV(J));
  OUTPUTO(1,/'//');
  END OUTCOV;
PROCEDURE INDATA(X,N);
INTEGER N; ARRAY X;
COMMENT READING OF DATA AND STORING IN THE ARRAY X. N=NUMBER OF DATA;
BEGIN INTEGER I,J;
  FOR I:=1 STEP 1 UNTIL N DO BEGIN
    FOR J:=1 STEP 1 UNTIL MIN(I+13,N) DO BEGIN
      INPUT1(3,/'-2ZDD',X(J));
      OUTPUT2(1,/'3ZD,-3ZDB',J,X(J));
    END J;
    INPUTO(3,/'/');
  END I;
  END INDATA;
INDATA(X,N);

```

```

00004170
00004180
00004190
00004200
00004210
00004220
00004230
00004240
00004250
00004260
00004270
00004280
00004290
00004300
00004310
00004320
00004330
00004820
00004830
00004840
00004850
00004860
00004870
00004880
00004890
00004900
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00004960
00004970
00004980
00004990
00005000
00005010
00005020
00005030
00005040
00005050
00005060
00005070
00005080
00005090
00005100
00005110
00005120
00005130
00005140
00005150
00005160
00005170
00005180
00005190
00005200
00005210
00005220
00005230
00005240

```

```

COMMENT CALCULATION AND OUTPUT OF MAX.LIK.ESTIMATES;
MAXLIK(N,PMAX,X,COV,INIT);
K:=0;
FOR P:=1 STEP 1 UNTIL PMAX DO BEGIN
  FOR J:=1 STEP 1 UNTIL P DO
    TH(J):=INIT(K+J);
    ETA:=INIT(K+P+1);
    SGM:=INIT(K+P+2);
    OUTPAR(P,1);
    K:=K+P+2;
  END P;
OUTCOV(PMAX);
COMMENT CALCULATION OF INITIAL ROBUST ESTIMATES;
MED:=MEDIAN(X,N);
SGM:=COV(0):=1.0;
FOR P:=1 STEP 1 UNTIL PMAX DO BEGIN
  INITIAL(N,X,P-1,P,TH,COV,SGM,MED,INIT);
  FOR J:=1 STEP 1 UNTIL P DO
    TH(J):=INIT(J);
    ETA:=INIT(P+1);
    SGM:=INIT(P+2);
    OUTPAR(P,2);
  COMMENT CALCULATION OF CMIN AND CMAX;
  IF P<5 THEN CMIN:=1.3+P*0.2
  ELSE IF P<9 THEN CMIN:=1.5+P*0.15
  ELSE CMIN:=0.34+SQRT(P)*0.82;
  IF P<3 THEN CMAX:=2.1+P*0.4
  ELSE IF P<5 THEN CMAX:=2.3+P*0.3
  ELSE IF P<7 THEN CMAX:=2.5+P*0.25
  ELSE IF P<10 THEN CMAX:=2.8+P*0.2
  ELSE CMAX:=0.52+SQRT(P)*1.37;
  COMMENT ITERATIVE CALCULATION OF FINAL ROBUST ESTIMATE FOR
  DIFFERENT VALUES OF C1 AND C2. ALWAYS ONE OF THE
  TWO CONSTANTS C1,C2 IS KEPT UNCHANGED. IF C1 CHANGES
  (I=3), WE START WITH ARPAR, IF C2 CHANGES (I=2,4) OR
  AT THE BEGINNING (I=1) WE START WITH NUISANCE;
  FOR I:=1 STEP 1 UNTIL 4 DO BEGIN
    IF I<3 THEN C1:=CMAX ELSE C1:=CMIN;
    IF REM(I,3)=1 THEN C2:=1.5 ELSE C2:=1.0;
    IF I=3 THEN BEGIN
      ARPAR(N,P,X,ETA,SGM,C1,TH,COV,NI);
      IF NI=11 THEN
        OUTPUTO(1,'"ITERATION FOR TH HAS NOT YET CONVERGED"/');
      END THEN;
    NUISANCE(N,P,X,TH,C2,ETA,SGM,NI);
    IF NI=11 THEN
      OUTPUTO(1,'"ITERATION FOR ETA/SGM HAS NOT YET CONVERGED"/');
    IF I=3 THEN OUTPAR(P,4);
    ARPAR(N,P,X,ETA,SGM,C1,TH,COV,NI);
    IF NI=11 THEN
      OUTPUTO(1,'"ITERATION FOR TH HAS NOT YET CONVERGED"/');
    IF I=3 & NI=1 THEN GOTO STOP;
    IF REM(I,3)>0 THEN OUTPAR(P,4);
    NIT:=1;
  FOR NIT:=NIT+1 WHILE NIT<11 DO BEGIN
    NUISANCE(N,P,X,TH,C2,ETA,SGM,NI);
    IF NI=1 THEN GOTO STOP;
    IF NI=11 THEN
      OUTPUTO(1,'"ITERATION FOR ETA/SGM HAS NOT YET CONVERGED"/');
    IF I=3 THEN OUTPAR(P,5);

```

```

ARPAR(N,P,X,ETA,SGM,C1,TH,COV,NI);
IF NI=1 THEN GOTO STOP;
IF NI=11 THEN
OUTPUTO(1,"ITERATION FOR TH HAS NOT YET CONVERGED"/');
IF REM(I,3)>0 THEN OUTPAR(P,5);
END WHILE;
STOP;
IF NIT=11 THEN
OUTPUTO(1,'/"OVERALL ITERATION HAS NOT YET CONVERGED"');
OUTPAR(P,3);
OUTCOV(P);
END I;
END P;
END; END
    
```

00005850  
00005860  
00005870  
00005880  
00005890  
00005900  
00005910  
00005920  
00005930  
00005940  
00005950  
00005960  
00005970  
00005980

R. DATA (ROBAR 出力例)

91	2	1	842	2	842	3	842	4	910	5	910	6	910	7	963
8	963	9	963	10	959	11	959	12	959	13	954	14	954	15	954
16	951	17	975	18	1175	19	995	20	987	21	1011	22	980	23	960
24	972	25	985	26	982	27	980	28	1184	29	1184	30	970	31	956
32	958	33	958	34	964	35	949	36	924	37	950	38	922	39	906
40	901	41	894	42	887	43	861	44	861	45	853	46	845	47	864
48	862	49	866	50	861	51	865	52	854	53	852	54	869	55	893
56	910	57	893	58	947	59	932	60	935	61	950	62	945	63	942
64	942	65	942	66	927	67	893	68	888	69	877	70	882	71	862
72	870	73	866	74	869	75	835	76	859	77	814	78	820	79	822
80	824	81	834	82	830	83	821	84	831	85	840	86	852	87	864
88	955	89	982	90	991	91	1000								

APPROXIMATED MAX. LIK. ESTIMATES FOR THE ORDER 1  
AR-PARAMETERS .789  
LOCATION OF DATA: 918.637 S.D. OF INNOVATIONS: 44.263

APPROXIMATED MAX. LIK. ESTIMATES FOR THE ORDER 2  
AR-PARAMETERS .766 .030  
LOCATION OF DATA: 918.637 S.D. OF INNOVATIONS: 44.243  
CORRESPONDING COVARIANCES FOR LAGS 0,..., 2  
5193.519530 4098.453120 3292.966800

CRUDE INITIAL ROBUST ESTIMATES FOR THE ORDER 1  
AR-PARAMETERS .950  
LOCATION OF DATA: 925.503 S.D. OF INNOVATIONS: 12.686  
INTERMEDIATE ESTIMATES IN THE RECURSIVE CALCULATION  
AR-PARAMETERS .958  
LOCATION OF DATA: 916.452 S.D. OF INNOVATIONS: 15.498

FINAL ESTIMATES WITH ROBUSTNESS CONSTANTS C1= 2.50, C2= 1.50 FOR THE ORDER 1  
AR-PARAMETERS .958  
LOCATION OF DATA: 917.961 S.D. OF INNOVATIONS: 15.436  
CORRESPONDING COVARIANCES FOR LAGS 0,..., 1  
2905.479490 2783.798830

INTERMEDIATE ESTIMATES IN THE RECURSIVE CALCULATION  
AR-PARAMETERS .959  
LOCATION OF DATA: 911.029 S.D. OF INNOVATIONS: 13.358

FINAL ESTIMATES WITH ROBUSTNESS CONSTANTS C1= 2.50, C2= 1.00 FOR THE ORDER 1  
 AR-PARAMETERS .959  
 LOCATION OF DATA: 911.048 S.D. OF INNOVATIONS: 13.334  
 CORRESPONDING COVARIANCES FOR LAGS 0,..., 1  
 2185.687740 2094.563720

INTERMEDIATE ESTIMATES IN THE RECURSIVE CALCULATION  
 AR-PARAMETERS .959  
 LOCATION OF DATA: 911.047 S.D. OF INNOVATIONS: 13.333

FINAL ESTIMATES WITH ROBUSTNESS CONSTANTS C1= 1.50, C2= 1.00 FOR THE ORDER 1  
 AR-PARAMETERS .959  
 LOCATION OF DATA: 911.047 S.D. OF INNOVATIONS: 13.333  
 CORRESPONDING COVARIANCES FOR LAGS 0,..., 1  
 2214.107180 2123.360110

INTERMEDIATE ESTIMATES IN THE RECURSIVE CALCULATION  
 AR-PARAMETERS .959  
 LOCATION OF DATA: 918.166 S.D. OF INNOVATIONS: 15.432

FINAL ESTIMATES WITH ROBUSTNESS CONSTANTS C1= 1.50, C2= 1.50 FOR THE ORDER 1  
 AR-PARAMETERS .959  
 LOCATION OF DATA: 918.253 S.D. OF INNOVATIONS: 15.430  
 CORRESPONDING COVARIANCES FOR LAGS 0,..., 1  
 2966.206050 2844.646240

CRUDE INITIAL ROBUST ESTIMATES FOR THE ORDER 2  
 AR-PARAMETERS .828 .136  
 LOCATION OF DATA: 930.333 S.D. OF INNOVATIONS: 15.475  
 INTERMEDIATE ESTIMATES IN THE RECURSIVE CALCULATION  
 AR-PARAMETERS .967 -.019  
 LOCATION OF DATA: 916.076 S.D. OF INNOVATIONS: 17.645  
 AR-PARAMETERS .976 -.022  
 LOCATION OF DATA: 918.049 S.D. OF INNOVATIONS: 15.493

FINAL ESTIMATES WITH ROBUSTNESS CONSTANTS C1= 2.90, C2= 1.50 FOR THE ORDER 2  
 AR-PARAMETERS .977 -.023  
 LOCATION OF DATA: 919.224 S.D. OF INNOVATIONS: 15.433  
 CORRESPONDING COVARIANCES FOR LAGS 0,..., 2  
 2685.132810 2563.224850 2441.580810

INTERMEDIATE ESTIMATES IN THE RECURSIVE CALCULATION  
 AR-PARAMETERS .991 -.030  
 LOCATION OF DATA: 913.316 S.D. OF INNOVATIONS: 13.111

FINAL ESTIMATES WITH ROBUSTNESS CONSTANTS C1= 2.90, C2= 1.00 FOR THE ORDER 2  
 AR-PARAMETERS .993 -.032  
 LOCATION OF DATA: 914.292 S.D. OF INNOVATIONS: 12.732  
 CORRESPONDING COVARIANCES FOR LAGS 0,..., 2  
 2152.637210 2069.927000 1985.484860

INTERMEDIATE ESTIMATES IN THE RECURSIVE CALCULATION  
 AR-PARAMETERS 1.002 -.031  
 LOCATION OF DATA: 916.062 S.D. OF INNOVATIONS: 12.468

FINAL ESTIMATES WITH ROBUSTNESS CONSTANTS C1= 1.70, C2= 1.00 FOR THE ORDER 2  
 AR-PARAMETERS 1.003 -.031  
 LOCATION OF DATA: 916.062 S.D. OF INNOVATIONS: 12.468  
 CORRESPONDING COVARIANCES FOR LAGS 0,..., 2  
 2802.237550 2723.333250 2641.896240

## INTERMEDIATE ESTIMATES IN THE RECURSIVE CALCULATION

AR-PARAMETERS 1.001 -.035  
 LOCATION OF DATA: 926.157 S.D. OF INNOVATIONS: 15.411

## FINAL ESTIMATES WITH ROBUSTNESS CONSTANTS C1= 1.70, C2= 1.50 FOR THE ORDER 2

AR-PARAMETERS 1.001 -.035  
 LOCATION OF DATA: 923.557 S.D. OF INNOVATIONS: 15.366  
 CORRESPONDING COVARIANCES FOR LAGS 0,..., 2  
 3644.482670 3524.294920 3399.832030

&gt;&gt;.

## CHECK

```

BEGIN COMMENT THIS PROGRAMME CONTAINS THREE PROCEDURES WHICH HELP 00000010
TO DETECT OUTLIERS AND OTHER IRREGULARITIES IN 00000020
TIME SERIES. IT IS ASSUMED THAT AN AR(P)-MODEL HAS 00000030
BEEN FITTED BY THE ROBUST ESTIMATION PROGRAMME 00000040
ROBAR.ALG. THE THREE PROCEDURES DO THE FOLLOWING: 00000050
INNOV LISTS ALL STANDARDIZED INNOVATIONS. LARGE 00000060
VALUES ARE RESPONSIBLE FOR DIFFERENCES BETWEEN 00000070
THE ROBUST AND THE NON-ROBUST ESTIMATES FOR 00000080
ETA:=E(X(I)) AND SGM:=S.D. OF THE INNOVATIONS. 00000090
CHISQ DETECTS THOSE Q-TUPLES OF CONSECUTIVE OBSER- 00000100
VATIONS WHICH DO NOT FIT TO THE MODEL. 00000110
WEIGHT GIVES THE DATA DEPENDENT WEIGHTS USED IN THE 00000120
ROBUST ESTIMATION. A WEIGHT << 1 MEANS THAT 00000130
THE CORRESPONDING (P+1)-TUPLE IS RESPONSIBLE 00000140
FOR A DIFFERENCE BETWEEN THE ROBUST AND THE 00000150
NON-ROBUST ESTIMATES FOR THE AUTOREGRESSIVE 00000160
PARAMETER. THE WEIGHTS ARE FORMED WITH THE 00000170
INNOVATIONS AND THE CHI-SQUARE STATISTIC FOR 00000180
THE PRECEDING P VALUES, SO FOR A MORE DE- 00000190
TAILED ANALYSIS ONE HAS TO LOOK AT THE OUT- 00000200
PUTS OF INNOV AND CHISQ. 00000210
INPUT: N=NUMBER OF DATA 00000220
P=ORDER OF THE MODEL 00000230
TH=AR-PARAMETERS 00000240
ETA=LOCATION OF THE DATA 00000250
SGM=S.D. OF THE INNOVATIONS 00000260
C=ROBUSTNESS CONSTANT USED FOR TH 00000270
X=DATA VECTOR 00000280
ARE READ IN THIS ORDER FROM THE FILE Y.DAT. 00000290
OUTPUT: THE OUTPUT FROM THE PROCEDURES INNOV, CHISQ 00000300
AND WEIGHT IS PRINTED ON THE FILE C.DAT; 00000310
INTEGER N,I,J,P; REAL C,ETA,SGM; 00000320
INPUT2(3,'B3ZD,B2ZD/',N,P); 00000330
OUTPUT2(1,'B3ZD,B2ZD',N,P); 00000340
OUTPUTO(1,'//'); 00000350
BEGIN ARRAY X(1:N), TH(1:P); 00000360
PROCEDURE PARCOR(P,TH,A); 00000370
VALUE P; INTEGER P; ARRAY TH,A; 00000380
COMMENT ADJUSTING AR-MODELS OF ORDER < P TO THE COVARIANCES 00000390
OF THE AR(P)-MODEL WITH PARAMETERS TH(1),...,TH(P) 00000400
AND SGM=1. 00000410

```



```

INPUT: TH. 00000420
OUTPUT: A, WHERE A(J,J)=1/(PREDICTION VARIANCE OF THE00000430
MODEL OF ORDER J-1) AND A(J,K)=K-TH COEFFICIENT OF TH00000440
MODEL OF ORDER J-1 (K<J); 00000450
BEGIN REAL Z; INTEGER I,J,K; 00000460
A(P+1,P+1):=1.0; 00000470
FOR I:=1 STEP 1 UNTIL P DO 00000480
  A(P+1,I):=TH(I); 00000490
  FOR J:=P STEP -1 UNTIL 2 DO BEGIN 00000500
    Z:=1/(1-A(J+1,J)**2); 00000510
    A(J,J-1):=(A(J+1,J-1)+A(J+1,J)*A(J+1,1))*Z; 00000520
    FOR K:=J-2 STEP -1 UNTIL 1 DO 00000530
      A(J,K):=(A(J+1,K)+A(J+1,J)*A(J+1,J-K))*Z; 00000540
    A(J,J):=A(J+1,J+1)/Z; 00000550
    END J; 00000560
  A(1,1):=A(2,2)*(1-A(2,1)**2); 00000570
  END PARCOR; 00000580
PROCEDURE INNOV(N,P,X,TH); 00000590
  INTEGER N,P; ARRAY X,TH; 00000600
  COMMENT CALCULATION OF THE INNOVATIONS FOR THE AR(P)-MODEL 00000610
  WITH PARAMETERS TH AND ETA=0. 00000620
  INPUT: 00000630
  N=NUMBER OF DATA 00000640
  P=ORDER OF THE MODEL 00000650
  X=DATA VECTOR 00000660
  TH=AR-PARAMETER 00000670
  THE RESULTS ARE PRINTED DURING THE PROCEDURE, 00000680
  FOR I=1,2,..P-1 EMPTY SPACES ARE PRINTED; 00000690
BEGIN INTEGER I,J; REAL U; 00000700
  FOR I:=1 STEP 1 UNTIL P DO 00000710
    SPACE(7); 00000720
    FOR I:=P+1 STEP 1 UNTIL N DO BEGIN 00000730
      U:=X(I); 00000740
      FOR J:=1 STEP 1 UNTIL P DO 00000750
        U:=U-TH(J)*X(I-J); 00000760
      OUTPUT1(1,'-7Z.3D',U); 00000770
      IF REM(I,5)=0 THEN OUTPUTO(1,'/'); 00000780
      END I; 00000790
    OUTPUTO(1,'//'); 00000800
  END INNOV; 00000810
PROCEDURE CHISQ(N,P,Q,X,TH); 00000820
  INTEGER N,P,Q; ARRAY X,TH; 00000830
  COMMENT THE CHI-SQUARE STATISTICS OF ALL Q-TUPLES (Q<=P) X(I-Q), 00000840
  ...,X(I-1) ARE CALCULATED BASED ON AN AR(P)-MODEL 00000850
  WITH PARAMETERS TH, ETA=0, SGM=1. 00000860
  INPUT: 00000870
  N=NUMBER OF DATA 00000880
  X=DATA VECTOR 00000890
  P=ORDER OF THE MODEL 00000900
  Q=NUMBER OF CONSECUTIVE DATA TO INVESTIGATE 00000910
  TH,ETA,SGM=PARAMETERS OF THE MODEL 00000920
  ALL RESULTS ARE PRINTED DURING THE PROCEDURE, 00000930
  FOR I=1,..,Q EMPTY SPACES ARE PRINTED; 00000940
BEGIN INTEGER I,J,K; REAL V,Z; 00000950
  ARRAY A(1:P+1,1:P+2); 00000960
  PARCOR(P,TH,A); 00000970
  FOR I:=1 STEP 1 UNTIL Q DO SPACE(7); 00000980
  FOR I:=Q+1 STEP 1 UNTIL N DO BEGIN 00000990
    Z:=0.0; 00001000
    FOR J:=0 STEP 1 UNTIL Q-1 DO BEGIN 00001010
      V:=X(I-Q+J); 00001020

```

```

FOR K:=1 STEP 1 UNTIL J DO                                00001030
  V:=V-A(J+1,K)*X(I-Q+J-K);                              00001040
  Z:=Z+A(J+1,J+1)*V**2;                                  00001050
  END J;                                                  00001060
OUTPUT1(1,'-7Z.2D',Z);                                   00001070
IF REM(I,5)=0 THEN OUTPUTO(1,'/');                      00001080
END I;                                                    00001090
OUTPUTO(1,'//');                                         00001100
END CHISQ;                                               00001110
PROCEDURE WEIGHT(N,P,X,TH,C);                             00001120
  INTEGER N,P; REAL C; ARRAY X,TH;                      00001130
  COMMENT CALCULATION OF THE FINAL WEIGHTS USED IN THE CAL- 00001140
  CULATION OF THE ROBUST ESTIMATES TH. THE WEIGHTS      00001150
  ARE MIN(C/(SQRT(Z)*ABS(U)),1) WHERE U IS THE INNOVATION 00001160
  AND Z THE CHI-SQUARE STATISTIC OF THE PRECEEDING P VALUE 00001170
  INPUT:                                                  00001180
    N=NUMBER OF DATA                                   00001190
    P=ORDER OF THE MODEL                               00001200
    X=DATA VECTOR                                     00001210
    TH=AUTOREGRESSIVE PARAMETER                       00001220
    C=ROBUSTNESS CONSTANT USED IN THE CALCULATION OF TH. 00001230
    THE WEIGHTS ARE PRINTED DURING THE PROCEDURE,      00001240
    FOR I=1,...,P EMPTY SPACES ARE PRINTED;          00001250
  BEGIN INTEGER I,J,K; REAL U,V,W,Z;                   00001260
    ARRAY A(1:P+1,1:P+2);                              00001270
    PARCOR(P,TH,A);                                    00001280
    FOR I:=1 STEP 1 UNTIL P DO SPACE(5);               00001290
    FOR I:=P+1 STEP 1 UNTIL N DO BEGIN                 00001300
      U:=X(I);                                          00001310
      FOR J:=1 STEP 1 UNTIL P DO                      00001320
        U:=U-TH(J)*X(I-J);                            00001330
      Z:=0.0;                                          00001340
      FOR J:=0 STEP 1 UNTIL P-1 DO BEGIN              00001350
        V:=X(I-P+J);                                  00001360
        FOR K:=1 STEP 1 UNTIL J DO                   00001370
          V:=V-A(J+1,K)*X(I-P+J-K);                 00001380
          Z:=Z+A(J+1,J+1)*V**2;                     00001390
        END J;                                        00001400
      W:=SQRT(Z)*ABS(U);                              00001410
      IF W<C THEN W:=1 ELSE W:=C/W;                 00001420
      OUTPUT1(1,'-6Z.3D',W);                         00001430
      IF REM(I,5)=0 THEN OUTPUTO(1,'/');            00001440
      END I;                                          00001450
    OUTPUTO(1,'//');                                  00001460
  END WEIGHT;                                           00001470
  FOR I:=1 STEP 1 UNTIL P DO BEGIN                    00001480
    INPUT1(3,'-2Z.3D',TH(I));                        00001490
    OUTPUT1(1,'-2Z.3D',TH(I));                      00001500
  END I;                                               00001510
  INPUT3(3,'-2Z.3D,-2Z.3D,ZZ.DD/',ETA,SGM,C);       00001520
  OUTPUT3(1,'-5Z.3D,-5Z.3D,ZZ.DD/',ETA,SGM,C);     00001530
  FOR I:=1 STEP 14 UNTIL N DO BEGIN                  00001540
    FOR J:=I STEP 1 UNTIL MIN(I+13,N) DO BEGIN      00001550
      INPUT1(3,'-2ZDD',X(J));                       00001560
    END J;                                           00001570
    INPUTO(3,'/');                                   00001580
  END I;                                              00001590
  FOR I:=1 STEP 5 UNTIL N DO BEGIN                   00001600
    FOR J:=I STEP 1 UNTIL MIN(I+4,N) DO BEGIN      00001610
      OUTPUT2(1,'4ZD,-7ZDB',J,X(J));                00001620
    END J;

```

```

END J;                                00001630
OUTPUTO(1, '/');                       00001640
END I;                                00001650
FOR I:=1 STEP 1 UNTIL N DO BEGIN       00001660
X(I):=(X(I)-ETA)/SGM;                  00001670
END I;                                00001680
INNOV(N,P,X,TH);                       00001690
CHISQ(N,P,P,X,TH);                     00001700
WEIGHT(N,P,X,TH,C);                    00001710
END;                                    00001720
END                                     00001730

```

## C. DATA (CHECK 出力例)

91 1

```

.959  911.000  13.300  1.50
  1      842      2      842      3      842      4      910      5      910
  6      910      7      963      8      963      9      963     10     959
 11     959     12     959     13     954     14     954     15     954
 16     951     17     975     18     1175    19     995     20     987
 21    1011     22     980     23     960     24     972     25     985
 26     982     27     980     28     1184    29     1184    30     970
 31     956     32     958     33     958     34     964     35     949
 36     924     37     950     38     922     39     906     40     901
 41     894     42     887     43     861     44     861     45     853
 46     845     47     864     48     862     49     866     50     861
 51     865     52     854     53     852     54     869     55     893
 56     910     57     893     58     947     59     932     60     935
 61     950     62     945     63     942     64     942     65     942
 66     927     67     893     68     888     69     877     70     882
 71     862     72     870     73     866     74     869     75     835
 76     859     77     814     78     820     79     822     80     824
 81     834     82     830     83     821     84     831     85     840
 86     852     87     864     88     955     89     982     90     991
 91    1000

```

```

-.213      -.213      4.900      -.003
-.003      3.982      .160      .160      -.140
.148      .148      -.228      .133      .133
-.093      1.928      15.235     -12.720     -.343
2.039     -2.023     -1.291      1.053      1.165
.003      .068      15.551      .842     -15.249
-.871      .289      .145      .596     -.964
-1.763     1.995     -1.985     -1.169     -.391
-.557     -.579     -2.029     -.154     -.756
-.780     1.225     -.295     .150     -.515
.147     -.969     -.326     1.096     1.675
1.223     -1.281     4.005     -1.017     .290
1.202     -.256     -.121     .096     .096
-1.032     -2.507     -.431     -.898     .271
-1.593     .450     -.427     .087     -2.686
1.570     -3.544     .152     -.130     -.124
.484     -.538     -.926     .474     .430
.683      .720     6.697     2.166     .896
.923

```

2.16	2.16	2.16	.00	
.00	.00	1.23	1.23	1.23
1.05	1.05	1.05	.84	.84
.84	.73	1.86	31.65	3.20
2.62	4.54	2.16	1.09	1.69
2.49	2.29	2.16	33.84	33.84
1.58	.92	1.00	1.00	1.28
.66	.08	.69	.05	.01
.05	.13	.26	1.14	1.14
1.53	1.98	1.00	1.09	.92
1.14	.96	1.48	1.58	.80
.15	.00	.15	.59	.20
.26	.69	.52	.44	.44
.44	.12	.15	.24	.52
.38	1.09	.76	.92	.80
2.62	1.23	4.27	3.76	3.60
3.44	2.69	2.98	3.68	2.91
2.29	1.58	1.00	.88	2.29
2.91				
1.000	1.000	.208	1.000	
1.000	1.000	1.000	1.000	1.000
1.000	1.000	1.000	1.000	1.000
1.000	.913	.072	.021	1.000
.454	.348	.790	1.000	.990
1.000	1.000	.066	.306	.017
1.000	1.000	1.000	1.000	1.000
1.000	1.000	.909	1.000	1.000
1.000	1.000	1.000	1.000	1.000
1.000	.871	1.000	1.000	1.000
1.000	1.000	1.000	1.000	1.000
1.000	1.000	.977	1.000	1.000
1.000	1.000	1.000	1.000	1.000
1.000	1.000	1.000	1.000	1.000
1.000	1.000	1.000	1.000	.624
.590	.382	1.000	1.000	1.000
1.000	1.000	.938	1.000	1.000
1.000	1.000	.224	.739	1.000
.953				

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